

Article 11

Terminate-and-Stay-Resident Utilities

The MS-DOS Terminate and Stay Resident system calls (Interrupt 21H Function 31H and Interrupt 27H) allow the programmer to install executable code or program data in a reserved block of RAM, where it resides while other programs execute. Global data, interrupt handlers, and entire applications can be made RAM-resident in this way. Programs that use the MS-DOS terminate-and-stay-resident capability are commonly known as TSR programs or TSRs.

This article describes how to install a TSR in RAM, how to communicate with the resident program, and how the resident program can interact with MS-DOS. The discussion proceeds from a general description of the MS-DOS functions useful to TSR programmers to specific details about certain MS-DOS structural elements necessary to proper functioning of a TSR utility and concludes with two programming examples.

Note: Microsoft cannot guarantee that the information in this article will be valid for future versions of MS-DOS.

Structure of a Terminate-and-Stay-Resident Utility

The executable code and data in TSRs can be separated into RAM-resident and transient portions (Figure 11-1). The RAM-resident portion of a TSR contains executable code and data for an application that performs some useful function on demand. The transient portion installs the TSR; that is, it initializes data and interrupt handlers contained in the RAM-resident portion of the program and executes an MS-DOS Terminate and Stay Resident function call that leaves the RAM-resident portion in memory and frees the memory used by the transient portion. The code in the transient portion of a TSR runs when the .EXE or .COM file containing the program is executed; the code in the RAM-resident portion runs only when it is explicitly invoked by a foreground program or by execution of a hardware or software interrupt.

TSRs can be broadly classified as passive or active, depending on the method by which control is transferred to the RAM-resident program. A passive TSR executes only when another program explicitly transfers control to it, either through a software interrupt or by means of a long JMP or CALL. The calling program is not interrupted by the TSR, so the status of MS-DOS, the system BIOS, and the hardware is well defined when the TSR program starts to execute.

In contrast, an active TSR is invoked by the occurrence of some event external to the currently running (foreground) program, such as a sequence of user keystrokes or a pre-defined hardware interrupt. Therefore, when it is invoked, an active TSR almost always



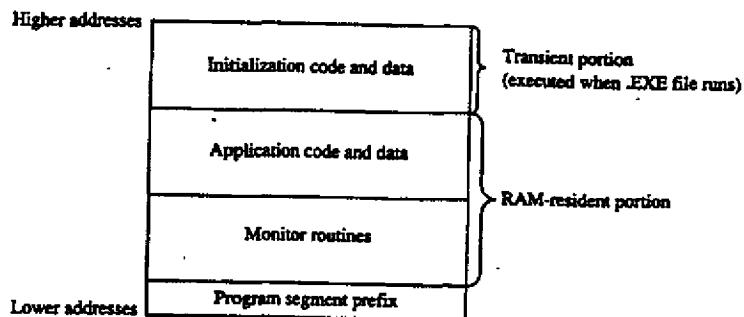


Figure 11-1. Organization of a TSR program in memory.

interrupts some other program and suspends its execution. To avoid disrupting the interrupted program, an active TSR must monitor the status of MS-DOS, the ROM BIOS, and the hardware and take control of the system only when it is safe to do so.

Passive TSRs are generally simpler in their construction than active TSRs because a passive TSR runs in the context of the calling program; that is, when the TSR executes, it assumes that it can use the calling program's program segment prefix (PSP), open files, current directory, and so on. See PROGRAMMING IN THE MS-DOS ENVIRONMENT: PROGRAMMING FOR MS-DOS: Structure of an Application Program. It is the calling program's responsibility to ensure that the hardware and MS-DOS are in a stable state before it transfers control to a passive TSR.

An active TSR, on the other hand, is invoked asynchronously; that is, the status of the hardware, MS-DOS, and the executing foreground program is indeterminate when the event that invokes the TSR occurs. Therefore, active TSRs require more complex code. The RAM-resident portion of an active TSR must contain modules that monitor the operating system to determine when control can safely be transferred to the application portion of the TSR. The monitor routines typically test the status of keyboard input, ROM BIOS interrupt processing, hardware interrupt processing, and MS-DOS function processing. The TSR activates the application (the part of the RAM-resident portion that performs the TSR's main task) only when it detects the appropriate keyboard input and determines that the application will not interfere with interrupt and MS-DOS function processing.

Keyboard input

An active TSR usually contains a RAM-resident module that examines keyboard input for a predetermined keystroke sequence called a "hot-key" sequence. A user executes the RAM-resident application by entering this hot-key sequence at the keyboard.

The technique used in the TSR to monitor keyboard input depends on the keyboard hardware implementation. On computers in the IBM PC and PS/2 families, the keyboard coprocessor generates an Interrupt 09H for each keypress. Therefore, a TSR can monitor user keystrokes by installing an interrupt handler (interrupt service routine, or ISR) for Interrupt 09H. This handler can thus detect a specified hot-key sequence.

ROM BIOS interrupt processing

The ROM BIOS routines in IBM PCs and PS/2s are not reentrant. An active TSR that calls the ROM BIOS must ensure that its code does not attempt to execute a ROM BIOS function that was already being executed by the foreground process when the TSR program took control of the system.

The IBM ROM BIOS routines are invoked through software interrupts, so an active TSR can monitor the status of the ROM BIOS by replacing the default interrupt handlers with custom interrupt handlers that intercept the appropriate BIOS interrupts. Each of these interrupt handlers can maintain a status flag, which it increments before transferring control to the corresponding ROM BIOS routine and decrements when the ROM BIOS routine has finished executing. Thus, the TSR monitor routines can test these flags to determine when non-reentrant BIOS routines are executing.

Hardware interrupt processing

The monitor routines of an active TSR, which may themselves be executed as the result of a hardware interrupt, should not activate the application portion of the TSR if any other hardware interrupt is being processed. On IBM PCs, for example, hardware interrupts are processed in a prioritized sequence determined by an Intel 8259A Programmable Interrupt Controller. The 8259A does not allow a hardware interrupt to execute if a previous interrupt with the same or higher priority is being serviced. All hardware interrupt handlers include code that signals the 8259A when interrupt processing is completed. (The programming interface to the 8259A is described in IBM's *Technical Reference* manuals and in Intel's technical literature.)

If a TSR were to interrupt the execution of another hardware interrupt handler before the handler signaled the 8259A that it had completed its interrupt servicing, subsequent hardware interrupts could be inhibited indefinitely. Inhibition of high-priority hardware interrupts such as the timer tick (Interrupt 08H) or keyboard interrupt (Interrupt 09H) could cause a system crash. For this reason, an active TSR must monitor the status of all hardware interrupt processing by interrogating the 8259A to ensure that control is transferred to the RAM-resident application only when no other hardware interrupts are being serviced.

MS-DOS function processing

Unlike the IBM ROM BIOS routines, MS-DOS is reentrant to a limited extent. That is, there are certain times when MS-DOS's servicing of an Interrupt 21H function call invoked by a foreground process can be suspended so that the RAM-resident application can make an Interrupt 21H function call of its own. For this reason, an active TSR must monitor operating system activity to determine when it is safe for the TSR application to make its calls to MS-DOS.

MS-DOS Support for Terminate-and-Stay-Resident Programs

Several MS-DOS system calls are useful for supporting terminate-and-stay-resident utilities. These are listed in Table 11-1. See SYSTEM CALLS.

Table 11-1. MS-DOS Functions Useful in TSR Programs.

Function Name	Call With	Returns	Comment
Terminate and Stay Resident	AH = 31H AL = return code DX = size of resident program (in 16-byte paragraphs) INT 21H	Nothing	Preferred over Interrupt 27H with MS-DOS versions 2.x and later
Terminate and Stay Resident	CS = PSP DX = size of resident program (bytes) INT 27H	Nothing	Provided for compatibility with MS-DOS versions 1.x
Set Interrupt Vector	AH = 25H AL = interrupt number DS:DX = address of interrupt handler INT 21H	Nothing	
Get Interrupt Vector	AH = 35H AL = interrupt number INT 21H	ES:BX = address of interrupt handler	
Set PSP Address	AH = 50H BX = PSP segment INT 21H	Nothing	
Get PSP Address	AH = 51H INT 21H	BX = PSP segment	
Set Extended Error Information	AX = 5D0AH DS:DX = address of 11-word data structure: word 0: register AX as returned by Function 59H word 1: register BX word 2: register CX word 3: register DX word 4: register SI word 5: register DI word 6: register DS word 7: register ES words 8-0AH: reserved; should be 0 INT 21H	Nothing	MS-DOS versions 3.1 and later

(more)

Table 11-1. *Continued.*

Function Name	Call With	Returns	Comment
Get Extended Error Information	AH = 59H BX = 0 INT 21H	AX = extended error code BH = error class BL = suggested action CH = error locus	
Set Disk Transfer Area Address	AH = 1AH DS:DX = address of DTA INT 21H	Nothing	
Get Disk Transfer Area Address	AH = 2FH INT 21H	ES:BX = address of current DTA	
Get InDOS Flag Address	AH = 34H INT 21H	ES:BX = address of InDOS flag	

Terminate-and-stay-resident functions

MS-DOS provides two mechanisms for terminating the execution of a program while leaving a portion of it resident in RAM. The preferred method is to execute Interrupt 21H Function 31H.

Interrupt 21H Function 31H

When this Interrupt 21H function is called, the value in DX specifies the amount of RAM (in paragraphs) that is to remain allocated after the program terminates, starting at the program segment prefix (PSP). The function is similar to Function 4CH (Terminate Process with Return Code) in that it passes a return code in AL, but it differs in that open files are not automatically closed by Function 31H.

Interrupt 27H

When Interrupt 27H is executed, the value passed in DX specifies the number of bytes of memory required for the RAM-resident program. MS-DOS converts the value passed in DX from bytes to paragraphs, sets AL to zero, and jumps to the same code that would be executed for Interrupt 21H Function 31H. Interrupt 27H is less flexible than Interrupt 21H Function 31H because it limits the size of the program that can remain resident in RAM to 64 KB; it requires that CS point to the base of the PSP, and it does not pass a return code. Later versions of MS-DOS support Interrupt 27H primarily for compatibility with versions 1.x.

TSR RAM management

In addition to the RAM explicitly allocated to the TSR by means of the value in DX, the RAM allocated to the TSR's environment remains resident when the installation portion of the TSR program terminates. (The paragraph address of the environment is found at

offset 2CH in the TSR's PSP.) Moreover, if the installation portion of a TSR program has used Interrupt 21H Function 48H (Allocate Memory Block) to allocate additional RAM, this memory also remains allocated when the program terminates. If the RAM-resident program does not need this additional RAM, the installation portion of the TSR program should free it explicitly by using Interrupt 21H Function 49H (Free Memory Block) before executing Interrupt 21H Function 31H.

Set and Get Interrupt Vector functions

Two Interrupt 21H function calls are available to inspect or update the contents of a specified 8086-family interrupt vector. Function 25H (Set Interrupt Vector) updates the vector of the interrupt number specified in the AL register with the segment and offset values specified in DS:DX. Function 35H (Get Interrupt Vector) performs the inverse operation: It copies the current vector of the interrupt number specified in AL into the ES:BX register pair.

Although it is possible to manipulate interrupt vectors directly, the use of Interrupt 21H Functions 25H and 35H is generally more convenient and allows for upward compatibility with future versions of MS-DOS.

Set and Get PSP Address functions

MS-DOS uses a program's PSP to keep track of certain data unique to the program, including command-line parameters and the segment address of the program's environment. See PROGRAMMING IN THE MS-DOS ENVIRONMENT: PROGRAMMING FOR MS-DOS: Structure of an Application Program. To access this information, MS-DOS maintains an internal variable that always contains the location of the PSP associated with the foreground process. When a RAM-resident application is activated, it should use Interrupt 21H Functions 50H (Set Program Segment Prefix Address) and 51H (Get Program Segment Prefix Address) to preserve the current contents of this variable and to update the variable with the location of its own PSP. Function 50H (Set Program Segment Prefix Address) updates an internal MS-DOS variable that locates the PSP currently in use by the foreground process. Function 51H (Get Program Segment Prefix Address) returns the contents of the internal MS-DOS variable to the caller.

Set and Get Extended Error Information functions

In MS-DOS versions 3.1 and later, the RAM-resident program should preserve the foreground process's extended error information so that, if the RAM-resident application encounters an MS-DOS error, the extended error information pertaining to the foreground process will still be available and can be restored. Interrupt 21H Functions 59H and 5D0AH provide a mechanism for the RAM-resident program to save and restore this information during execution of a TSR application.

Function 59H (Get Extended Error Information), which became available in version 3.0, returns detailed information on the most recently detected MS-DOS error. The inverse operation is performed by Function 5D0AH (Set Extended Error Information), which can be used only in MS-DOS versions 3.1 and later. This function copies extended error information to MS-DOS from a data structure defined in the calling program.

Set and Get Disk Transfer Area Address functions

Several MS-DOS data transfer functions, notably Interrupt 21H Functions 21H, 22H, 27H, and 28H (the Random Read and Write functions) and Interrupt 21H Functions 14H and 15H (the Sequential Read and Write functions), require a program to specify a disk transfer area (DTA). By default, a program's DTA is located at offset 80H in its program segment prefix. If a RAM-resident application calls an MS-DOS function that uses a DTA, the TSR should save the DTA address belonging to the interrupted program by using Interrupt 21H Function 2FH (Get Disk Transfer Area Address), supply its own DTA address to MS-DOS using Interrupt 21H Function 1AH (Set Disk Transfer Area Address), and then, before terminating, restore the interrupted program's DTA.

The MS-DOS idle interrupt (Interrupt 28H)

Several of the first 12 MS-DOS functions (01H through 0CH) must wait for the occurrence of an expected event such as a user keypress. These functions contain an "idle loop" in which looping continues until the event occurs. To provide a mechanism for other system activity to take place while the idle loop is executing, these MS-DOS functions execute an Interrupt 28H from within the loop.

The default MS-DOS handler for Interrupt 28H is only an IRET instruction. By supplying its own handler for Interrupt 28H, a TSR can perform some useful action at times when MS-DOS is otherwise idle. Specifically, a custom Interrupt 28H handler can be used to examine the current status of the system to determine whether or not it is safe to activate the RAM-resident application.

Determining MS-DOS Status

A TSR can infer the current status of MS-DOS from knowledge of its internal use of stacks and from a pair of internal status flags. This status information is essential to the proper execution of an active TSR because a RAM-resident application can make calls to MS-DOS only when those calls will not disrupt an earlier call made by the foreground process.

MS-DOS internal stacks

MS-DOS versions 2.0 and later may use any of three internal stacks: the I/O stack (*IOSStack*), the disk stack (*DiskStack*), and the auxiliary stack (*AuxStack*). In general, *IOSStack* is used for Interrupt 21H Functions 01H through 0CH and *DiskStack* is used for the remaining Interrupt 21H functions; *AuxStack* is normally used only when MS-DOS has detected a critical error and subsequently executed an Interrupt 24H. See PROGRAMMING IN THE MS-DOS ENVIRONMENT: CUSTOMIZING MS-DOS: Exception Handlers. Specifically, MS-DOS's internal stack use depends on which MS-DOS function is being executed and on the value of the critical error flag.

The critical error flag

The critical error flag (*ErrorMode*) is a 1-byte flag that MS-DOS uses to indicate whether or not a critical error has occurred. During normal, errorless execution, the value of the

critical error flag is zero. Whenever MS-DOS detects a critical error, it sets this flag to a nonzero value before it executes Interrupt 24H. If an Interrupt 24H handler subsequently invokes an MS-DOS function by using Interrupt 21H, the nonzero value of the critical error flag tells MS-DOS to use its auxiliary stack for Interrupt 21H Functions 01H through 0CH instead of using the I/O stack as it normally would.

In other words, when control is transferred to MS-DOS through Interrupt 21H, the function number and the critical error flag together determine MS-DOS stack use for the function. Figure 11-2 outlines the internal logic used on entry to an MS-DOS function to select which stack is to be used during processing of the function. As stated above, for Functions 01H through 0CH, MS-DOS uses *IOStack* if the critical error flag is zero and *AuxStack* if the flag is nonzero. For function numbers greater than 0CH, MS-DOS usually uses *DiskStack*, but Functions 50H, 51H, and 59H are important exceptions. Functions 50H and 51H use either *IOStack* (in versions 2.x) or the stack supplied by the calling program (in versions 3.x). In version 3.0, Function 59H uses either *IOStack* or *AuxStack*, depending on the value of the critical error flag, but in versions 3.1 and later, Function 59H always uses *AuxStack*.

MS-DOS versions 2.x

```

if  (FunctionNumber >= 01H and FunctionNumber <= 0CH)
or
FunctionNumber = 50H
or
FunctionNumber = 51H

then if  ErrorMode = 0
      then use IOStack
      else use AuxStack

else ErrorMode = 0
      use DiskStack

```

MS-DOS version 3.0

```

if  FunctionNumber = 50H
or
FunctionNumber = 51H
or
FunctionNumber = 62H

then use caller's stack

else if  (FunctionNumber >= 01H and FunctionNumber <= 0CH)
or
Function Number = 59H

      then if  ErrorMode = 0
            then use IOStack
            else use AuxStack

      else ErrorMode = 0
            use DiskStack

```

Figure 11-2. Strategy for use of MS-DOS internal stacks.

(more)

MS-DOS versions 3.1 and later

```

if FunctionNumber = 33H
or
FunctionNumber = 50H
or
FunctionNumber = 51H
or
FunctionNumber = 62H

then use caller's stack

else if (FunctionNumber >= 01H and FunctionNumber <= 0CH)

    then if ErrorMode = 0
        then use IOStack
        else use AuxStack

    else if FunctionNumber = 59H
        then use AuxStack
        else ErrorMode = 0
            use DiskStack

```

Figure 11-2. Continued.

This scheme makes Functions 01H through 0CH reentrant in a limited sense, in that a substitute critical error (Interrupt 24H) handler invoked while the critical error flag is nonzero can still use these Interrupt 21H functions. In this situation, because the flag is nonzero, *AuxStack* is used for Functions 01H through 0CH instead of *IOStack*. Thus, if *IOStack* is in use when the critical error is detected, its contents are preserved during the handler's subsequent calls to these functions.

The stack-selection logic differs slightly between MS-DOS versions 2 and 3. In versions 3.x, a few functions—notably 50H and 51H—avoid using any of the MS-DOS stacks. These functions perform uncomplicated tasks that make minimal demands for stack space, so the calling program's stack is assumed to be adequate for them.

The InDOS flag

InDOS is a 1-byte flag that is incremented each time an Interrupt 21H function is invoked and decremented when the function terminates. The flag's value remains nonzero as long as code within MS-DOS is being executed. The value of InDOS does not indicate which internal stack MS-DOS is using.

Whenever MS-DOS detects a critical error, it zeros InDOS before it executes Interrupt 24H. This action is taken to accommodate substitute Interrupt 24H handlers that do not return control to MS-DOS. If InDOS were not zeroed before such a handler gained control, its value would never be decremented and would therefore be incorrect during subsequent calls to MS-DOS.

The address of the 1-byte InDOS flag can be obtained from MS-DOS by using Interrupt 21H Function 34H (Return Address of InDOS Flag). In versions 3.1 and later, the 1-byte critical error flag is located in the byte preceding InDOS, so, in effect, the address of both

flags can be found using Function 34H. Unfortunately, there is no easy way to find the critical error flag in other versions. The recommended technique is to scan the MS-DOS segment, which is returned in the ES register by Function 34H, for one of the following sequences of instructions:

```
test    ss:[CriticalSectionFlag],0FFH      ;(versions 3.1 and later)
jne    NearLabel
push   ss:[NearWord]
int    28H
```

Or

```
cmp    ss:[CriticalSectionFlag],00      ;(versions earlier than 3.1)
jne    NearLabel
int    28H
```

When the TEST or CMP instruction has been identified, the offset of the critical error flag can be obtained from the instruction's operand field.

The Multiplex Interrupt

The MS-DOS multiplex interrupt (Interrupt 2FH) provides a general mechanism for a program to verify the presence of a TSR and communicate with it. A program communicates with a TSR by placing an identification value in AH and a function number in AL and issuing an Interrupt 2FH. The TSR's Interrupt 2FH handler compares the value in AH to its own predetermined ID value. If they match, the TSR's handler keeps control and performs the function specified in the AL register. If they do not match, the TSR's handler relinquishes control to the previously installed Interrupt 2FH handler. (Multiplex ID values 00H through 7FH are reserved for use by MS-DOS; therefore, user multiplex numbers should be in the range 80H through OFFH.)

The handler in the following example recognizes only one function, corresponding to AL = 00H. In this case, the handler returns the value 0FFH in AL, signifying that the handler is indeed resident in RAM. Thus, a program can detect the presence of the handler by executing Interrupt 2FH with the handler's ID value in AH and 00H in AL.

```
mov    ah,MultiplexID
mov    al,00H
int    2FH
cmp    al,0FFH
je    AlreadyInstalled
```

To ensure that the identification byte is unique, its value should be determined at the time the TSR is installed. One way to do this is to pass the value to the TSR program as a command-line parameter when the TSR program is installed. Another approach is to place the identification value in an environment variable. In this way, the value can be found in the environment of both the TSR and any other program that calls Interrupt 2FH to verify the TSR's presence.

In practice, the multiplex interrupt can also be used to pass information to and from a RAM-resident program in the CPU registers, thus providing a mechanism for a program to share control or status information with a TSR.

TSR Programming Examples

One effective way to become familiar with TSRs is to examine functional programs. Therefore, the subsequent pages present two examples: a simple passive TSR and a more complex active TSR.

HELLO.ASM

The "bare-bones" TSR in Figure 11-3 is a passive TSR. The RAM-resident application, which simply displays the message *Hello, World*, is invoked by executing a software interrupt. This example illustrates the fundamental interactions among a RAM-resident program, MS-DOS, and programs that execute after the installation of the RAM-resident utility.

```
; ; Name:          hello
; ;
; Description:   This RAM-resident (terminate-and-stay-resident) utility
;                 displays the message "Hello, World" in response to a
;                 software interrupt.
; ;
; Comments:      Assemble and link to create HELLO.EXE.
; ;
;                 Execute HELLO.EXE to make resident.
; ;
;                 Execute INT 64h to display the message.
;

TSRInt    EQU     64h
STDOUT     EQU     1

RESIDENT_TEXT SEGMENT byte public 'CODE'
ASSUME cs:RESIDENT_TEXT,ds:RESIDENT_DATA

TSRAction  PROC    far
            sti             ; enable interrupts
            push  ds           ; preserve registers
            push  ax
            push  bx
            push  cx
            push  dx


```

Figure 11-3. HELLO.ASM, a passive TSR.

(more)

```

        mov    dx,seg RESIDENT_TEXT
        mov    ds,dx
        mov    dx,offset Message      ; DS:DX -> message
        mov    cx,16                  ; CX = length
        mov    bx,STDOUT              ; BX = file handle
        mov    ah,40h                  ; AH = INT 21H function 40H
                                       ; (Write File)
        int    21h                  ; display the message

        pop    dx                    ; restore registers and exit
        pop    cx
        pop    bx
        pop    ax
        pop    ds
        iret

TSRAction    ENDP

RESIDENT_TEXT ENDS

RESIDENT_DATA SEGMENT word public 'DATA'
Message      DB      0Dh,0Ah,'Hello, World',0Dh,0Ah
RESIDENT_DATA ENDS

TRANSIENT_TEXT SEGMENT para public 'TCODE'
ASSUME cs:TRANSIENT_TEXT,ss:TRANSIENT_STACK

HelloTSR PROC far           ; At entry:   CS:IP -> SnapTSR
                           ; SS:SP -> stack
                           ; DS,ES -> PSP
                           ; Install this TSR's interrupt handler

        mov    ax,seg RESIDENT_TEXT
        mov    ds,ax
        mov    dx,offset RESIDENT_TEXT:TSRAction
        mov    al,TSRInt
        mov    ah,25h
        int    21h

        ; Terminate and stay resident

        mov    dx,cs      ; DX = paragraph address of start of
                           ; transient portion (end of resident
                           ; portion)
        mov    ax,es      ; ES = PSP segment
        sub    dx,ax      ; DX = size of resident portion

```

Figure 11-3. Continued.

(more)

```

        mov     ax,3100h      ; AH = INT 21H function number (TSR)
        int     21h          ; AL = 00H (return code)

HelloTSR      ENDP

TRANSIENT_TEXT    ENDS

TRANSIENT_STACK SEGMENT word stack 'TSTACK'
DB      80h dup(?)
TRANSIENT_STACK ENDS

END      HelloTSR

```

Figure 11-3. Continued.

The transient portion of the program (in the segments *TRANSIENT_TEXT* and *TRANSIENT_STACK*) runs only when the file HELLO.EXE is executed. This installation code updates an interrupt vector to point to the resident application (the procedure *TSRAction*) and then calls Interrupt 21H Function 31H to terminate execution, leaving the segments *RESIDENT_TEXT* and *RESIDENT_DATA* in RAM.

The order in which the code and data segments appear in the listing is important. It ensures that when the program is executed as a .EXE file, the resident code and data are placed in memory at lower addresses than the transient code and data. Thus, when Interrupt 21H Function 31H is called, the memory occupied by the transient portion of the program is freed without disrupting the code and data in the resident portion.

The RAM containing the resident portion of the utility is left intact by MS-DOS during subsequent execution of other programs. Thus, after the TSR has been installed, any program that issues the software interrupt recognized by the TSR (in this example, Interrupt 64H) will transfer control to the routine *TSRAction*, which uses Interrupt 21H Function 40H to display a simple message on standard output.

Part of the reason this example is so short is that it performs no error checking. A truly reliable version of the program would check the version of MS-DOS in use, verify that the program was not already installed in memory, and chain to any previously installed interrupt handlers that use the same interrupt vector. (The next program, SNAP.ASM, illustrates these techniques.) However, the primary reason the program is small is that it makes the basic assumption that MS-DOS, the ROM BIOS, and the hardware interrupts are all stable at the time the resident utility is executed.

SNAP.ASM

The preceding assumption is a reliable one in the case of the passive TSR in Figure 11-3, which executes only when it is explicitly invoked by a software interrupt. However, the situation is much more complicated in the case of the active TSR in Figure 11-4. This

program is relatively long because it makes no assumptions about the stability of the operating environment. Instead, it monitors the status of MS-DOS, the ROM BIOS, and the hardware interrupts to decide when the RAM-resident application can safely execute.

```
; Name: snap
;
; Description: This RAM-resident (terminate-and-stay-resident) utility
; produces a video "snapshot" by copying the contents of the
; video regeneration buffer to a disk file. It may be used
; in 80-column alphanumeric video modes on IBM PCs and PS/2s.
;
; Comments: Assemble and link to create SNAP.EXE.
;
; Execute SNAP.EXE to make resident.
;
; Press Alt-Enter to dump current contents of video buffer
; to a disk file.
;

MultiplexID EQU 0CAh ; unique INT 2FH ID value
TSRStackSize EQU 100h ; resident stack size in bytes
KB_FLAG EQU 17h ; offset of shift-key status flag in
; ROM BIOS keyboard data area
KBIns EQU 80h ; bit masks for KB_FLAG
KBCaps EQU 40h
KBNum EQU 20h
KBScroll EQU 10h
KBAlt EQU 8
KBCtrl EQU 4
KBLeft EQU 2
KBRight EQU 1
SCEnter EQU 1Ch

CR EQU 0Dh
LF EQU 0Ah
TRUE EQU -1
FALSE EQU 0

PAGE
-----
; RAM-resident routines
-----

RESIDENT_GROUP GROUP RESIDENT_TEXT,RESIDENT_DATA,RESIDENT_STACK
```

Figure 11-4. SNAP.ASM, a video snapshot TSR.

(more)

```

RESIDENT_TEXT SEGMENT byte public 'CODE'
ASSUME CS:RESIDENT_GROUP, DS:RESIDENT_GROUP

;-----  

; System verification routines  

;-----  

VerifyDOSState PROC NEAR ; Returns: carry flag set if MS-DOS  

;                         ; is busy  

;                         ; preserve these registers
    push DS
    push BX
    push AX

    LDS BX,CS:ErrorModeAddr
    MOV AH,[BX]           ; AH = ErrorMode flag

    LDS BX,CS:InDOSAddr
    MOV AL,[BX]           ; AL = InDOS flag

    XOR BX,BX             ; BH = 00H, BL = 00H
    CMP BL,CS:InISR28    ; carry flag set if INT 28H handler
;                         ; is running
    RCL BL,1               ; BL = 01H if INT 28H handler is running
    CMP BX,AX              ; carry flag zero if AH = 00H
;                         ; and AL <= BL
    POP AX                ; restore registers
    POP BX
    POP DS
    RET

VerifyDOSState ENDP

VerifyIntState PROC NEAR ; Returns: carry flag set if hardware
;                         ; or ROM BIOS unstable
    PUSH AX               ; preserve AX

; Verify hardware interrupt status by interrogating Intel 8259A Programmable
; Interrupt Controller

    MOV AX,00001011B      ; AH = 0
;                         ; AL = OCW3 for Intel 8259A (RR = 1,
;                         ; RIS = 1)
    OUT 20H,AL             ; request 8259A's in-service register
    JMP L10:               ; wait a few cycles
    IN  AL,20H              ; AL = hardware interrupts currently
;                         ; being serviced (bit = 1 if in-service)

L10:

```

Figure II-4. Continued.

(more)

MS-PCA 1186440
CONFIDENTIAL

Part C: Customizing MS-DOS

```
        cmp     ah,al
        jc      L11          ; exit if any hardware interrupts still
                           ; being serviced

; Verify status of ROM BIOS interrupt handlers

        xor     al,al          ; AL = 00H

        cmp     al,cs:InISR5
        jc      L11          ; exit if currently in INT 05H handler

        cmp     al,cs:InISR9
        jc      L11          ; exit if currently in INT 09H handler

        cmp     al,cs:InISR10
        jc     L11          ; exit if currently in INT 10H handler

        cmp     al,cs:InISR13 ; set carry flag if currently in
                           ; INT 13H handler
L11:   pop    ax          ; restore AX and return
        ret

VerifyIntState ENDP

VerifyTSRState PROC near           ; Returns: carry flag set if TSR
                           ; inactive
        rol    cs:HotFlag,1 ; carry flag set if (HotFlag = TRUE)
        cmc
        jc      L20          ; carry flag set if (HotFlag = FALSE)
                           ; exit if no hot key

        ror    cs:ActiveTSR,1 ; carry flag set if (ActiveTSR = TRUE)
        jc      L20          ; exit if already active

        call   VerifyDOSState
        jc      L20          ; exit if MS-DOS unstable

        call   VerifyIntState ; set carry flag if hardware or BIOS
                           ; unstable
L20:   ret

VerifyTSRState ENDP

PAGE
;-----  
; System monitor routines  
;-----
```

```
ISR5    PROC far           ; INT 05H handler
                           ; (ROM BIOS print screen)
        inc    cs:InISR5       ; increment status flag
```

Figure 11-4. Continued.

(more)

```
        pushf
        cli
        call    cs:PrevISR5      ; chain to previous INT 05H handler
        dec    cs:InISR5       ; decrement status flag
        iret

ISR5      ENDP

ISR8      PROC    far      ; INT 08H handler (timer tick, IRQ0)
        pushf
        cli
        call    cs:PrevISR8      ; chain to previous handler
        cmp    cs:InISR8,0
        jne    L31                ; exit if already in this handler
        inc    cs:InISR8       ; increment status flag
        sti
        call    VerifyTSRState   ; interrupts are ok
        jc     L30                ; jump if TSR is inactive
        mov    byte ptr cs:ActiveTSR,TRUE
        call    TSRapp
        mov    byte ptr cs:ActiveTSR,FALSE
L30:      dec    cs:InISR8
L31:      iret
ISR8      ENDP

ISR9      PROC    far      ; INT 09H handler
                    ; (keyboard interrupt IRQ1)
        push    ds
        push    ax
        push    bx
                    ; preserve these registers
        push    cs
        pop    ds
                    ; DS -> RESIDENT_GROUP
        in     al,60h      ; AL = current scan code
        pushf
        cli
        call    ds:PrevISR9      ; let previous handler execute
```

Figure II-4. Continued.

(more)

```

        mov     ah,ds:InISR9    ; if already in this handler ..
        or      ah,ds:HotFlag   ; .. or currently processing hot key ..
        jnz     L43             ; .. jump to exit

        inc     ds:InISR9      ; increment status flag
        sti     ds:InISR9      ; now interrupts are ok

; Check scan code sequence

        cmp     ds:HotSeqLen,0
        je     L40             ; jump if no hot sequence to match

        mov     bx,ds:HotIndex
        cmp     al,[bx+HotSequence] ; test scan code sequence
        jne     L41             ; jump if no match

        inc     bx
        cmp     bx,ds:HotSeqLen
        jb     L42             ; jump if not last scan code to match

; Check shift-key state

L40:    push    ds
        mov     ax,40h
        mov     ds,ax            ; DS -> ROM BIOS data area
        mov     al,ds:[KB_FLAG]; AH = ROM BIOS shift-key flags
        pop     ds

        and     al,ds:HotKBMask; AL = flags AND "don't care" mask
        cmp     al,ds:HotKBFlag
        jne     L42             ; jump if shift state does not match

; Set flag when hot key is found

        mov     byte ptr ds:HotFlag,TRUE

L41:    xor     bx,bx          ; reinitialize index

L42:    mov     ds:HotIndex,bx ; update index into sequence
        dec     ds:InISR9       ; decrement status flag

L43:    pop     bx            ; restore registers and exit
        pop     ax
        pop     ds
        iret

ISR9    ENDP

```

Figure 11-4. Continued.

(more)

```
ISR10      PROC    far      ; INT 10H handler (ROM BIOS video I/O)
            inc     cs:InISR10   ; increment status flag
            pushf
            cli
            call    cs:PrevISR10 ; chain to previous INT 10H handler
            dec     cs:InISR10   ; decrement status flag
            iret

ISR10      ENDP

ISR13      PROC    far      ; INT 13H handler
            inc     cs:InISR13   ; (ROM BIOS fixed disk I/O)
            ; increment status flag
            pushf
            cli
            call    cs:PrevISR13 ; chain to previous INT 13H handler
            pushf
            dec     cs:InISR13   ; preserve returned flags
            popf
            ; decrement status flag
            ; restore flags register
            sti
            ret    2             ; enable interrupts
            ; simulate IRET without popping flags
            ; simulate IRET without popping flags

ISR13      ENDP

ISR1B      PROC    far      ; INT 1BH trap (ROM BIOS Ctrl-Break)
            mov     byte ptr cs:Trap1B,TRUE
            iret

ISR1B      ENDP

ISR23      PROC    far      ; INT 23H trap (MS-DOS Ctrl-C)
            mov     byte ptr cs:Trap23,TRUE
            iret

ISR23      ENDP

ISR24      PROC    far      ; INT 24H trap (MS-DOS critical error)
            mov     byte ptr cs:Trap24,TRUE
            iret
```

Figure 11-4. Continued.

(more)

Part C: Customizing MS-DOS

```
xor    al,al      ; AL = 00H (MS-DOS 2.x);
cmp    cs:MajorVersion,2 ; ignore the error
je     L50

mov    al,3      ; AL = 03H (MS-DOS 3.x);
          ; fail the MS-DOS call in which
          ; the critical error occurred

L50:    iret

ISR24  ENDP

ISR28  PROC  far   ; INT 28H handler
          ; (MS-DOS idle interrupt)
pushf
cli
call   cs:PrevISR28 ; chain to previous INT 28H handler
cmp   cs:InISR28,0
jne   L61      ; exit if already inside this handler
inc   cs:InISR28 ; increment status flag
call   VerifyTSRState
jc    L60      ; jump if TSR is inactive
mov   byte ptr cs:ActiveTSR,TRUE
call   TSRapp
mov   byte ptr cs:ActiveTSR,FALSE

L60:    dec   cs:InISR28 ; decrement status flag
L61:    iret

ISR28  ENDP

ISR2F  PROC  far   ; INT 2FH handler
          ; (MS-DOS multiplex interrupt)
          ; Caller: AH = handler ID
          ;          AL = function number
          ; Returns for function 0: AL = OFFH
          ; for all other functions: nothing
cmp   ah,MultiplexID
je    L70      ; jump if this handler is requested
jmp   cs:PrevISR2F ; chain to previous INT 2FH handler
```

Figure 11-4. Continued.

(more)

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```

L70:      test    al,al
          jnz     MultiplexIRET ; jump if reserved or undefined function
; Function 0: get installed state
          mov     al,0FFh      ; AL = OFFH (this handler is installed)
MultiplexIRET: iret      ; return from interrupt
ISR2F      ENDP

PAGE
;
;
; AuxInt21--sets ErrorMode while executing INT 21H to force use of the
; AuxStack instead of the IOStack.
;
;

AuxInt21 PROC near      ; Caller: registers for INT 21H
; Returns: registers from INT 21H
          push    ds
          push    bx
          lds    bx,ErrorModeAddr
          inc    byte ptr [bx]   ; ErrorMode is now nonzero
          pop    bx
          pop    ds

          int    21h      ; perform MS-DOS function

          push    ds
          push    bx
          lds    bx,ErrorModeAddr
          dec    byte ptr [bx]   ; restore ErrorMode
          pop    bx
          pop    ds
          ret

AuxInt21 ENDP

Int21v      PROC near      ; perform INT 21H or AuxInt21,
; depending on MS-DOS version
          cmp    DOSVersion,30AH
          jb     L80      ; jump if earlier than 3.1
          int    21h      ; versions 3.1 and later
          ret

```

Figure II-4. Continued.

(more)

```

L80:      call     AuxInt21    ; versions earlier than 3.1
          ret

Int21v     ENDP

PAGE
;-----  

; RAM-resident application  

;-----  

TSRapp     PROC    near
; Set up a safe stack

        push    ds      ; save previous DS on previous stack
        push    cs
        pop     ds      ; DS -> RESIDENT_GROUP
        mov     PrevSP,sp
        mov     PrevSS,ss  ; save previous SS:SP
        mov     ss,TSRSS
        mov     sp,TSRSP  ; SS:SP -> RESIDENT_STACK
        push    es      ; preserve remaining registers
        push    ax
        push    bx
        push    cx
        push    dx
        push    si
        push    di
        push    bp
        cld      ; clear direction flag
; Set break and critical error traps

        mov     cx,NTTrap
        mov     si,offset RESIDENT_GROUP:StartTrapList
L90:      lodsb    ; AL = interrupt number
          ; DS:SI -> byte past interrupt number
        mov     byte ptr [si],FALSE ; zero the trap flag
        push    ax      ; preserve AX
        mov     ah,35h   ; INT 21H function 35H
        ; (get interrupt vector)
        int     21h    ; ES:BX = previous interrupt vector
        mov     [si+1],bx ; save offset and segment ..
        mov     [si+3],es ; .. of previous handler

```

Figure II-4. Continued.

(more)

```

pop    ax          ; AL = interrupt number
mov    dx,[si+5]   ; DS:DX -> this TSR's trap
mov    ah,25h      ; INT 21H function 25H
int    21h         ; (set interrupt vector)
add    si,7        ; DS:SI -> next in list

loop   190

; Disable MS-DOS break checking during disk I/O

mov    ax,3300h    ; AH = INT 21H function number
                  ; AL = 00H (request current break state)
int    21h         ; DL = current break state
mov    PrevBreak,d1 ; preserve current state

xor    dl,dl       ; DL = 00H (disable disk I/O break
                  ; checking)
mov    ax,3301h    ; AL = 01H (set break state)
int    21h

; Preserve previous extended error information

cmp    DOSVersion,30Ah
jb     L91         ; jump if MS-DOS version earlier
                  ; than 3.1
push   ds          ; preserve DS
xor    bx,bx       ; BX = 00H (required for function 59H)
mov    ah,59h      ; INT 21H function 59H
call   Int21v      ; (get extended error info)

mov    cs:PrevExtErrDS,ds
pop    ds
mov    PrevExtErrAX,ax ; preserve error information
mov    PrevExtErrBX,bx ; in data structure
mov    PrevExtErrCX,cx
mov    PrevExtErrDX,dx
mov    PrevExtErrSI,si
mov    PrevExtErrDI,di
mov    PrevExtErrES,es

; Inform MS-DOS about current PSP

L91:   mov    ah,51h      ; INT 21H function 51H (get PSP address)
call   Int21v      ; BX = foreground PSP

        mov    PrevPSP,bx      ; preserve previous PSP

        mov    bx,TSRPSP      ; BX = resident PSP
        mov    ah,50h      ; INT 21H function 50H (set PSP address)
call   Int21v

```

Figure 11-4. Continued.

(more)

```

; Inform MS-DOS about current DTA (not really necessary in this application
; because DTA is not used)

        mov     ah,2Fh      ; INT 21H function 2Fh
        int     21h         ; (get DTA address) into ES:BX
        mov     PrevDTAoffs,bx
        mov     PrevDTAseg,es

        push    ds          ; preserve DS
        mov     ds,TSRPSP
        mov     dx,80h       ; DS:DX -> default DTA at PSP:0080H
        mov     ah,1Ah       ; INT 21H function 1AH
        int     21h         ; (set DTA address)
        pop     ds          ; restore DS

; Open a file, write to it, and close it

        mov     ax,0E07h     ; AH = INT 10H function number
                            ; (write teletype)
                            ; AL = 07H (bell character)
        int     10h         ; emit a beep

        mov     dx,offset RESIDENT_GROUP:SnapFile
        mov     ah,3Ch       ; INT 21H function 3CH
                            ; (create file handle)
        mov     cx,0          ; file attribute
        int     21h
        jc     L94         ; jump if file not opened

        push    ax          ; push file handle
        mov     ah,0Fh       ; INT 10H function 0FH (get video status)
        int     10h         ; AL = video mode number
                            ; AH = number of character columns
        pop     bx          ; BX = file handle

        cmp     ah,80
        jne     L93         ; jump if not 80-column mode

        mov     dx,0B800h     ; DX = color video buffer segment
        cmp     al,3
        jbe     L92         ; jump if color alphanumeric mode

        cmp     al,7
        jne     L93         ; jump if not monochrome mode

        mov     dx,0B000h     ; DX = monochrome video buffer segment

L92:   push    ds
        mov     ds,dx
        xor     dx,dx
        mov     cx,80*25*2   ; CX = number of bytes to write
        mov     ah,40h       ; INT 21H function 40H (write file)

```

Figure II-4. Continued.

(more)

```

        int    21h
        pop   ds

L93:     mov    ah,3Eh      ; INT 21H function 3EH (close file)
        int    21h

        mov    ax,0E07h      ; emit another beep
        int    10h

; Restore previous DTA

L94:     push   ds          ; preserve DS
        lds    dx,PrevDTA    ; DS:DX -> previous DTA
        mov    ah,1Ah      ; INT 21H function 1AH (set DTA address)
        int    21h
        pop    ds

; Restore previous PSP

        mov    bx,PrevPSP    ; BX = previous PSP
        mov    ah,50h      ; INT 21H function 50H
        call   Int21v      ; (set PSP address)

; Restore previous extended error information

        mov    ax,DOSVersion
        cmp    ax,30Ah
        jb    L95         ; jump if MS-DOS version earlier than 3.1
        cmp    ax,0A00h
        jae   L95         ; jump if MS OS/2-DOS 3.x box

        mov    dx,offset RESIDENT_GROUP:PrevExtErrInfo
        mov    ax,500Ah
        int    21h         ; (restore extended error information)

; Restore previous MS-DOS break checking

L95:     mov    dl,PrevBreak   ; DL = previous state
        mov    ax,3301h
        int    21h

; Restore previous break and critical error traps

        mov    cx,NTrap
        mov    si,offset RESIDENT_GROUP:StartTrapList
        push   ds          ; preserve DS

L96:     lods   byte ptr cs:[si] ; AL = interrupt number
                ; ES:SI -> byte past interrupt number
        lds    dx,cs:[si+1]  ; DS:DX -> previous handler
        mov    ah,25h      ; INT 21H function 25H
        int    21h         ; (set interrupt vector)

```

Figure 11-4. Continued.

(more)

Part C: Customizing MS-DOS

```
        add    si,7          ; DS:SI -> next in list
        loop   L96
        pop    ds             ; restore DS

; Restore all registers

        pop    bp
        pop    di
        pop    si
        pop    dx
        pop    cx
        pop    bx
        pop    ax
        pop    es

        mov    ss,PrevSS      ; SS:SP -> previous stack
        mov    sp,PrevSP
        pop    ds             ; restore previous DS

; Finally, reset status flag and return

        mov    byte ptr cs:NotFlag, FALSE
        ret

TSRapp    ENDP

RESIDENT_TEXT ENDS

RESIDENT_DATA SEGMENT word public 'DATA'

ErrorModeAddr DD    ?           ; address of MS-DOS ErrorMode flag
InDOSAddr     DD    ?           ; address of MS-DOS InDOS flag

NISR       DW    (EndISRList-StartISRList)/8 ; number of installed ISRs

StartISRList DB    05h          ; INT number
InISR5      DB    FALSE         ; flag
PrevISR5    DD    ?           ; address of previous handler
                DW    offset RESIDENT_GROUP:ISR5

InISR8      DB    08h          ; INT number
PrevISR8    DB    FALSE         ; flag
DD    ?           ; address of previous handler
                DW    offset RESIDENT_GROUP:ISR8

InISR9      DB    09h          ; INT number
PrevISR9    DB    FALSE         ; flag
DD    ?           ; address of previous handler
                DW    offset RESIDENT_GROUP:ISR9

InISR10     DB    10h          ; INT number
DB    FALSE         ; flag
```

Figure 11-4. Continued.

(more)

```

PrevISR10      DD      ?
                  DW      offset RESIDENT_GROUP:ISR10

InISR13        DB      13h
PrevISR13      DB      FALSE
                  DD      ?
                  DW      offset RESIDENT_GROUP:ISR13

InISR28        DB      28h
PrevISR28      DB      FALSE
                  DD      ?
                  DW      offset RESIDENT_GROUP:ISR28

InISR2F        DB      2Fh
PrevISR2F      DB      FALSE
                  DD      ?
                  DW      offset RESIDENT_GROUP:ISR2F

EndISRList     LABEL   BYTE

TSRPSP         DW      ?           ; resident PSP
TSRSP          DW      TSRStackSize ; resident SS:SP
TSRSS           DW      seg RESIDENT_STACK
PrevPSP         DW      ?           ; previous PSP
PrevSSP         DW      ?           ; previous SS:SP
PrevSS          DW      ?

HotIndex        DW      0           ; index of next scan code in sequence
HotSeqLen       DW      EndHotSeq-HotSequence ; length of hot-key sequence

HotSequence     DB      SCenter    ; hot sequence of scan codes
EndHotSeq       LABEL   BYTE

HotKBFlag       DB      KBALT     ; hot value of ROM BIOS KB_FLAG
HotKBMask      DB      (KBIns OR KBCaps OR KBNum OR KBScroll) XOR DFFh
HotFlag         DB      FALSE

ActivetSR       DB      FALSE

DOSVersion      LABEL   WORD
                  DB      ?           ; minor version number
MajorVersion    DB      ?           ; major version number

; The following data is used by the TSR application:

NTrap          DW      (EndTrapList-StartTrapList)/8 ; number of traps
StartTrapList   DB      1Bh
Trap1B          DB      FALSE
PrevISR1B      DD      ?
                  DW      offset RESIDENT_GROUP:ISR1B
                  DB      23h

```

Figure II-4. Continued.

(more)

Part C: Customizing MS-DOS

```
Trap23      DB      FALSE
PrevISR23   DD      ?
DW          offset RESIDENT_GROUP:ISR23

Trap24      DB      24h
PrevISR24   DB      FALSE
DD          ?
DW          offset RESIDENT_GROUP:ISR24

EndTrapList LABEL  BYTE

PrevBreak    DB      ?           ; previous break-checking flag

PrevDTA      LABEL  DWORD        ; previous DTA address
PrevDTAoffs  DW      ?
PrevDTAseg   DW      ?

PrevExtErrInfo LABEL  BYTE        ; previous extended error information
PrevExtErrAX  DW      ?
PrevExtErrBX  DW      ?
PrevExtErrCX  DW      ?
PrevExtErrDX  DW      ?
PrevExtErrSI  DW      ?
PrevExtErrDI  DW      ?
PrevExtErrDS  DW      ?
PrevExtErrES  DW      ?
DW          3 dup(0)

SnapFile     DB      '\snap.img' ; output filename in root directory

RESIDENT_DATA ENDS

RESIDENT_STACK SEGMENT word stack 'STACK'
DB          TSRStackSize dup(?)

RESIDENT_STACK ENDS

PAGE
;-----;
; Transient installation routines
;-----;

TRANSIENT_TEXT SEGMENT para public 'TCODE'
ASSUME cs:TRANSIENT_TEXT,ds:RESIDENT_DATA,ss:RESIDENT_STACK

InstallSnapTSR PROC far           ; At entry: CS:IP -> InstallSnapTSR
;                               ; SS:SP -> stack
;                               ; DS,ES -> PSP
```

Figure 11-4. Continued.

(more)

```

; Save PSP segment

        mov     ax,seg RESIDENT_DATA
        mov     ds,ax          ; DS -> RESIDENT_DATA

        mov     TSRPSP,es      ; save PSP segment

; Check the MS-DOS version

        call    GetDOSVersion ; AH = major version number
                           ; AL = minor version number

; Verify that this TSR is not already installed
;
; Before executing INT 2FH in MS-DOS versions 2.x, test whether INT 2FH
; vector is in use. If so, abort if PRINT.COM is using it.
;
; {Thus, in MS-DOS 2.x, if both this program and PRINT.COM are used,
; this program should be made resident before PRINT.COM.}

        cmp     ah,2
        ja     L101           ; jump if version 3.0 or later

        mov     ax,352Fh         ; AH = INT 21H function number
                           ; AL = interrupt number
        int    21h             ; ES:BX = INT 2FH vector

        mov     ax,es
        or     ax,bx
        jnz   L100           ; jump if current INT 2FH vector ...
                           ; ... is nonzero

        push   ds
        mov     ax,252Fh         ; AH = INT 21H function number
                           ; AL = interrupt number
        mov     dx,seg RESIDENT_GROUP
        mov     ds,dx
        mov     dx,offset RESIDENT_GROUP:MultiplexIRET

        int    21h           ; point INT 2FH vector to IRET
        pop     ds
        jmp    short L103       ; jump to install this TSR

L100:   mov     ax,0FF00h         ; look for PRINT.COM:
        int    2Fh             ; if resident, AH = print queue length;
                           ; otherwise, AH is unchanged

        cmp     ah,0FFh         ; if PRINT.COM is not resident ..
        je     L101           ; .. use multiplex interrupt

        mov     al,1
        call   FatalError      ; abort if PRINT.COM already installed

```

Figure 11-4. Continued.

(more)

Part C: Customizing MS-DOS

```
L101:      mov     ah,MultiplexID ; AH = multiplex interrupt ID value
            xor     al,al      ; AL = 00H
            int     2Fh       ; multiplex interrupt

            test    al,al
            jz     L103       ; jump if ok to install

            cmp     al,0FFh
            jne     L102       ; jump if not already installed

            mov     al,2
            call    FatalError ; already installed

L102:      mov     al,3
            call    FatalError ; can't install

; Get addresses of InDOS and ErrorMode flags

L103:      call    GetDOSFlags

; Install this TSR's interrupt handlers

            push   es        ; preserve PSP segment

            mov    cx,NISR
            mov    si,offset StartISRLList

L104:      lodsb      ; AL = interrupt number
            push   ax        ; DS:SI -> byte past interrupt number
            mov    ah,35h
            int    21h       ; preserve AX
            mov    [si+1],bx ; INT 21H function 35H
            mov    [si+3],es ; ES:BX = previous interrupt vector
            mov    [si+5],es ; save offset and segment ..
            mov    [si+7],es ; .. of previous handler

            pop    ax        ; AL = interrupt number
            push   ds        ; preserve DS
            mov    dx,[si+5]
            mov    bx,seg RESIDENT_GROUP
            mov    ds,bx      ; DS:DX -> this TSR's handler
            mov    ah,25h
            int    21h       ; INT 21H function 25H
            pop    ds        ; restore DS
            add    si,7       ; DS:SI -> next in list
            loop   L104

; Free the environment

            pop    es        ; ES = PSP segment
            push   es        ; preserve PSP segment
            mov    es,es:[2Ch] ; ES = segment of environment
```

Figure 11-4. Continued.

(more)

```

        mov     ah,49h      ; INT 21H function 49H
        int     21h      ; (free memory block)

; Terminate and stay resident

        pop     ax
        mov     dx,cs      ; AX = PSP segment
        mov     dx,cs      ; DX = paragraph address of start of
                           ; transient portion (end of resident
                           ; portion)
        sub     dx,ax      ; DX = size of resident portion

        mov     ax,3100h      ; AH = INT 21H function number
                           ; AL = 00H (return code)
        int     21h

InstallSnapTSR ENDP

GetDOSVersion PROC near      ; Caller: DS = seg RESIDENT_DATA
                           ; Returns: ES = PSP
                           ;          AH = major version
                           ;          AL = minor version
ASSUME ds:RESIDENT_DATA

        mov     ah,30h      ; INT 21H function 30H:
                           ; (get MS-DOS version)
        int     21h
        cmp     al,2
        jb      L110      ; jump if versions 1.x

        xchg   ah,al      ; AH = major version
                           ; AL = minor version
        mov     DOSVersion,ax      ; save with major version in
                           ; high-order byte
        ret

L110:    mov     al,00h
        call    FatalError      ; abort if versions < 1.x

GetDOSVersion ENDP
GetDOSFlags PROC near      ; Caller: DS = seg RESIDENT_DATA
                           ; Returns: InDOSAddr -> InDOS
                           ;          ErrorModeAddr -> ErrorMode
                           ; Destroys: AX,BX,CX,DI
ASSUME ds:RESIDENT_DATA

; Get InDOS address from MS-DOS

        push   es
        mov     ah,34h      ; INT 21H function number
        int     21h      ; ES:BX -> InDOS

```

Figure II-4. Continued.

(more)

```
        mov    word ptr InDOSAddr,bx
        mov    word ptr InDOSAddr+2,es

; Determine ErrorMode address

        mov    word ptr ErrorModeAddr+2,es      ; assume ErrorMode is
                                                ; in the same segment
                                                ; as InDOS

        mov    ax,DOSVersion
        cmp    ax,30Ah
        jb     L120       ; jump if MS-DOS version earlier
                        ; than 3.1 ..
        cmp    ax,0A00h
        jae   L120       ; .. or MS OS/2-DOS 3.x box

        dec    bx          ; in MS-DOS 3.1 and later, ErrorMode
        mov    word ptr ErrorModeAddr,bx      ; is just before InDOS
        jmp    short L125

L120:           ; scan MS-DOS segment for ErrorMode

        mov    cx,0FFFFh      ; CX = maximum number of bytes to scan
        xor    di,di          ; ES:DI -> start of MS-DOS segment

L121:           mov    ax,word ptr cs:LF2 ; AX = opcode for INT 28H

L122:           repne scash      ; scan for first byte of fragment
        jne   L126       ; jump if not found

        cmp    ah,es:[di]      ; inspect second byte of opcode
        jne   L122       ; jump if not INT 28H

        mov    ax,word ptr cs:LF1 + 1 ; AX = opcode for CMP
        cmp    ax,es:[di](LF1-LF2)
        jne   L123       ; jump if opcode not CMP

        mov    ax,es:[di](LF1-LF2)+2 ; AX = offset of ErrorMode
        jmp    short L124      ; in DOS segment

L123:           mov    ax,word ptr cs:LF3 + 1 ; AX = opcode for TEST
        cmp    ax,es:[di](LF3-LF4)
        jne   L121       ; jump if opcode not TEST

        mov    ax,es:[di](LF3-LF4)+2 ; AX = offset of ErrorMode

L124:           mov    word ptr ErrorModeAddr,ax

L125:           pop    es
        ret
```

Figure II-4. Continued.

(more)

MS-PCA 1186457
CONFIDENTIAL

MSC 00131500

```

; Come here if address of ErrorMode not found

L126:    mov     al,04h
          call    FatalError

; Code fragments for scanning for ErrorMode flag

LFnear   LABEL  near           ; dummy labels for addressing
LFbyte   LABEL  byte
LFword   LABEL  word

LF1:      cmp     ss:LFbyte,0       ; MS-DOS versions earlier than 3.1
jne     LFnear
LF2:      int     28h
          test    ss:LFbyte,0FFh ; TEST ErrorMode,0FFH
jne     LFnear
push    ss:LFword
LF4:      int     28h

GetDOSFlags ENDP

FatalError PROC  near           ; Caller: AL = message number
                                ; ES = PSP
ASSUME ds:TRANSIENT_DATA

push   ax           ; save message number on stack
mov    bx,seg TRANSIENT_DATA
mov    ds,bx

; Display the requested message

        mov     bx,offset MessageTable
        xor     ah,ah           ; AX = message number
        shl     ax,1            ; AX = offset into MessageTable
        add     bx,ax            ; DS:BX -> address of message
        mov     dx,[bx]           ; DS:BX -> message
        mov     ah,09h           ; INT 21H function 09H (display string)
        int     21h             ; display error message

        pop     ax           ; AL = message number
        or      al,al
        jz     L130            ; jump if message number is zero
                                ; (MS-DOS versions 1.x)

; Terminate (MS-DOS 2.x and later)

        mov     ah,4Ch           ; INT 21H function 4CH
        int     21h             ; (terminate process with return code)

```

Figure II-4. Continued.

(more)

Part C: Customizing MS-DOS

```
; Terminate (MS-DOS 1.x)

L130      PROC    far
          push   es           ; push PSP:0000H
          xor    ax,ax
          push   ax
          ret    far return (jump to PSP:0000H)
L130      ENDP
FatalError ENDP

TRANSIENT_TEXT ENDS

PAGE
;
;
; Transient data segment
;
;

TRANSIENT_DATA SEGMENT word public 'DATA'

MessageTable DW Message0      ; MS-DOS version error
              DW Message1      ; PRINT.COM found in MS-DOS 2.x
              DW Message2      ; already installed
              DW Message3      ; can't install
              DW Message4      ; can't find flag

Message0    DB CR,LF,'TSR requires MS-DOS 2.0 or later version',CR,LF,'$'
Message1    DB CR,LF,'Can''t install TSR: PRINT.COM active',CR,LF,'$'
Message2    DB CR,LF,'This TSR is already installed',CR,LF,'$'
Message3    DB CR,LF,'Can''t install this TSR',CR,LF,'$'
Message4    DB CR,LF,'Unable to locate MS-DOS ErrorMode flag',CR,LF,'$'

TRANSIENT_DATA ENDS

END      InstallSnapTSR
```

Figure 11-4. Continued.

When installed, the SNAP program monitors keyboard input until the user types the hot-key sequence Alt-Enter. When the hot-key sequence is detected, the monitoring routine waits until the operating environment is stable and then activates the RAM-resident application, which dumps the current contents of the computer's video buffer into the file SNAP.IMG. Figure 11-5 is a block diagram of the RAM-resident and transient components of this TSR.

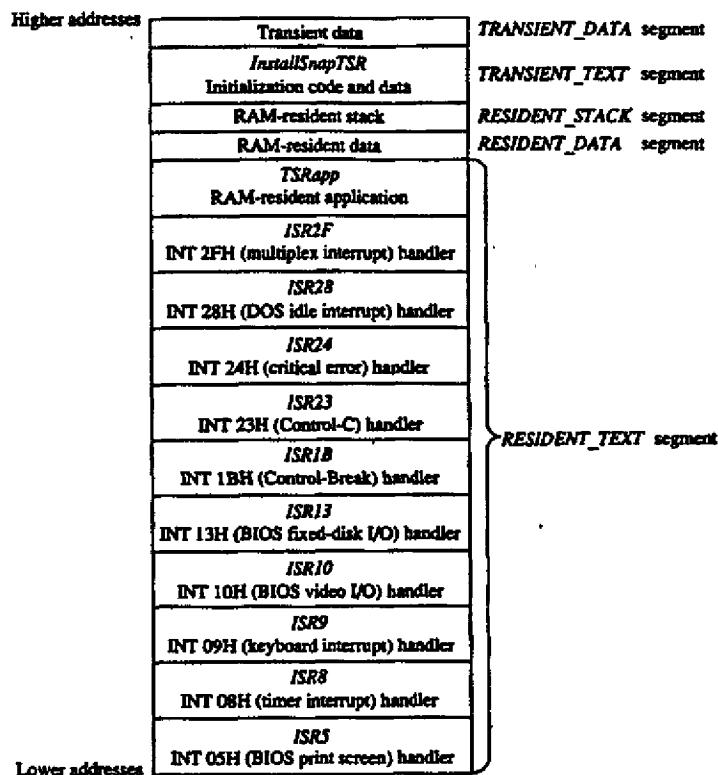


Figure 11-5. Block structure of the TSR program SNAP.EXE when loaded into memory. (Compare with Figure 11-1.)

Installing the program

When SNAP.EXE is run, only the code in the transient portion of the program is executed. The transient code performs several operations before it finally executes Interrupt 21H Function 31H (Terminate and Stay Resident). First it determines which MS-DOS version is in use. Then it executes the multiplex interrupt (Interrupt 2FH) to discover whether the resident portion has already been installed. If an MS-DOS version earlier than 2.0 is in use or if the resident portion has already been installed, the program aborts with an error message.

Otherwise, installation continues. The addresses of the InDOS and critical error flags are saved in the resident data segment. The interrupt service routines in the RAM-resident portion of the program are installed by updating all relevant interrupt vectors. The transient code then frees the RAM occupied by the program's environment, because the resident

portion of this program never uses the information contained there. Finally, the transient portion of the program, which includes the *TRANSIENT_TEXT* and *TRANSIENT_DATA* segments, is discarded and the program is terminated using Interrupt 21H Function 31H.

Detecting a hot key

The SNAP program detects the hot-key sequence (Alt-Enter) by monitoring each keypress. On IBM PCs and PS/2s, each keystroke generates a hardware interrupt on IRQ1 (Interrupt 09H). The TSR's Interrupt 09H handler compares the keyboard scan code corresponding to each keypress with a predefined sequence. The TSR's handler also inspects the shift-key status flags maintained by the ROM BIOS Interrupt 09H handler. When the predetermined sequence of keypresses is detected at the same time as the proper shift keys are pressed, the handler sets a global status flag (*HotFlag*).

Note how the TSR's handler transfers control to the previous Interrupt 09H ISR before it performs its own work. If the TSR's Interrupt 09H handler did not chain to the previous handler(s), essential system processing of keystrokes (particularly in the ROM BIOS Interrupt 09H handler) might not be performed.

Activating the application

The TSR monitors the status of *HotFlag* by regularly testing its value within a timer-tick handler. On IBM PCs and PS/2s, the timer-tick interrupt occurs on IRQ0 (Interrupt 08H) roughly 18.2 times per second. This hardware interrupt occurs regardless of what else the system is doing, so an Interrupt 08H ISR a convenient place to check whether *HotFlag* has been set.

As in the case of the Interrupt 09H handler, the TSR's Interrupt 08H handler passes control to previous Interrupt 08H handlers before it proceeds with its own work. This procedure is particularly important with Interrupt 08H because the ROM BIOS Interrupt 08H handler, which maintains the system's time-of-day clock and resets the system's Intel 8259A Programmable Interrupt Controller, must execute before the next timer tick can occur. The TSR's handler therefore defers its own work until control has returned after previous Interrupt 08H handlers have executed.

The only function of the TSR's Interrupt 08H handler is to attempt to transfer control to the RAM-resident application. The routine *VerifyTSRState* performs this task. It first examines the contents of *HotFlag* to determine whether a hot-key sequence has been detected. If so, it examines the state of the MS-DOS InDOS and critical error flags, the current status of hardware interrupts, and the current status of any non-reentrant ROM BIOS routines that might be executing.

If *HotFlag* is nonzero, the InDOS and critical error flags are both zero, no hardware interrupts are currently being serviced, and no non-reentrant ROM BIOS code has been interrupted, the Interrupt 08H handler activates the RAM-resident utility. Otherwise, nothing happens until the next timer tick, when the handler executes again.

While *HotFlag* is nonzero, the Interrupt 08H handler continues to monitor system status until MS-DOS, the ROM BIOS, and the hardware interrupts are all in a stable state. Often

the system status is stable at the time the hot-key sequence is detected, so the RAM-resident application runs immediately. Sometimes, however, system activities such as prolonged disk reads or writes can preclude the activation of the RAM-resident utility for several seconds after the hot-key sequence has been detected. The handler could be designed to detect this situation (for example, by decrementing *HotFlag* on each timer tick) and return an error status or display a message to the user.

A more serious difficulty arises when the MS-DOS default command processor (COMMAND.COM) is waiting for keyboard input. In this situation, Interrupt 21H Function 01H (Character Input with Echo) is executing, so *InDOS* is nonzero and the Interrupt 08H handler can never detect a state in which it can activate the RAM-resident utility. This problem is solved by providing a custom handler for Interrupt 28H (the MS-DOS idle interrupt), which is executed by Interrupt 21H Function 01H each time it loops as it waits for a keypress. The only difference between the Interrupt 28H handler and the Interrupt 08H handler is that the Interrupt 28H handler can activate the RAM-resident application when the value of *InDOS* is 1, which is reasonable because *InDOS* must have been incremented when Interrupt 21H Function 01H started to execute.

The interrupt service routines for ROM BIOS Interrupts 05H, 10H, and 13H do nothing more than increment and decrement flags that indicate whether these interrupts are being processed by ROM BIOS routines. These flags are inspected by the TSR's Interrupt 08H and 28H handlers.

Executing the RAM-resident application

When the RAM-resident application is first activated, it runs in the context of the program that was interrupted; that is, the contents of the registers, the video display mode, the current PSP, and the current DTA all belong to the interrupted program. The resident application is responsible for preserving the registers and updating MS-DOS with its PSP and DTA values.

The RAM-resident application preserves the previous contents of the CPU registers on its own stack to avoid overflowing the interrupted program's stack. It then installs its own handlers for Control-Break (Interrupt 1BH), Control-C (Interrupt 23H), and critical error (Interrupt 24H). (Otherwise, the interrupted program's handlers would take control if the user pressed Ctrl-Break or Ctrl-C or if an MS-DOS critical error occurred.) These handlers perform no action other than setting flags that can be inspected later by the RAM-resident application, which could then take appropriate action.

The application uses Interrupt 21H Functions 50H and 51H to update MS-DOS with the address of its PSP. If the application is running under MS-DOS versions 2.x, the critical error flag is set before Functions 50H and 51H are executed so that *AccStack* is used for the call instead of *IOSStack*, to avoid corrupting *IOSStack* in the event that *InDOS* is 1.

The application preserves the current extended error information with a call to Interrupt 21H Function 59H. Otherwise, the RAM-resident application might be activated immediately after a critical error occurred in the interrupted program but before the interrupted

program had executed Function 59H and, if a critical error occurred in the TSR application, the interrupted program's extended error information would inadvertently be destroyed.

This example also shows how to update the MS-DOS default DTA using Interrupt 21H Functions 1AH and 2FH, although in this case this step is not necessary because the DTA is never used within the application. In practice, the DTA should be updated only if the RAM-resident application includes calls to Interrupt 21H functions that use a DTA (Functions 11H, 12H, 14H, 15H, 21H, 22H, 27H, 28H, 4EH, and 4FH).

After the resident interrupt handlers are installed and the PSP, DTA, and extended error information have been set up, the RAM-resident application can safely execute any Interrupt 21H function calls except those that use *IOStack* (Functions 01H through 0CH). These functions cannot be used within a RAM-resident application even if the application sets the critical error flag to force the use of the auxiliary stack, because they also use other non-reentrant data structures such as input/output buffers. Thus, a RAM-resident utility must rely either on user-written console input/output functions or, as in the example, on ROM BIOS functions.

The application terminates by returning the interrupted program's extended error information, DTA, and PSP to MS-DOS, restoring the previous Interrupt 1BH, 23H, and 24H handlers, and restoring the previous CPU registers and stack.

Richard Wilton